Analysis Of Quality Control Data: Faults Prediction In Case of Significant Noise and Imbalance

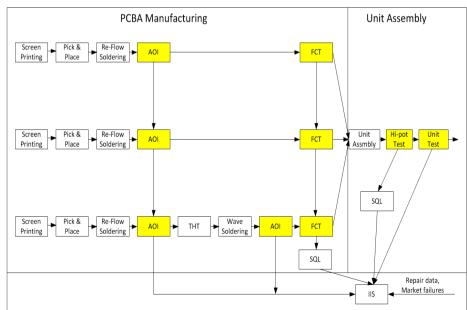
Abdul Rauf Khan, Henrik Schiøler, Torben Knudsen, Murat Kulahci and Mohamed Zaki



Manufacturing Process (Of Industrial Partner)









Manufacturing Process (Of Industrial Partner)

Objective:

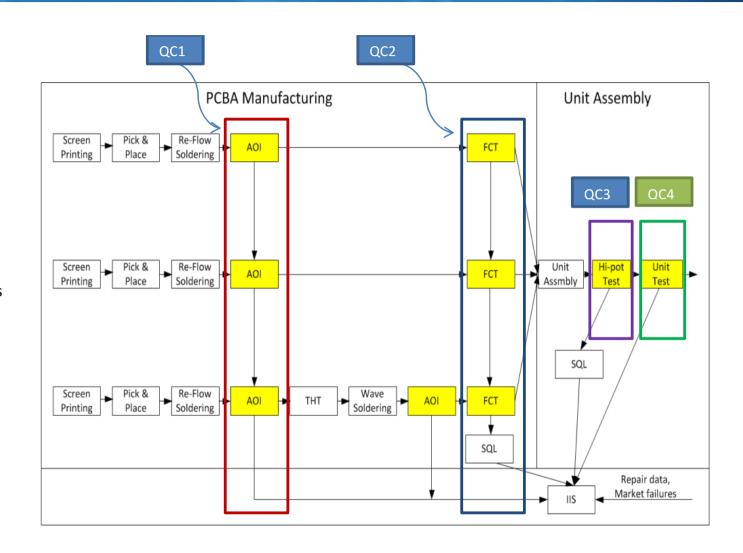
Prediction of quality at last quality control stage

Challenges:

- Multi stage Manufacturing Process
- Heterogeneous Data streams

Gains:

- Optimization of resources
- · Process understanding





Exploratory Analysis

A	В	С	D	E	F	G	○ !	1
Nr	Board 1 Vision	Board 1 Function	Board 2 Vision	Board 2 Function	Board 3 Function	VLTHSP	VLT Unit	Freq
1	F	F	-	F	F	F	F	0
2	P	F	F	F	F	F	\smile	0
3	R	F	F	F	F	F	F	0
4	F	P	F	F	F	F	F	0
5	P	P	F	F	F	F	F	0
6	R	P	F	F	F	F	F	0
7	F	R	F	F	F	F	F	0
8	P	R	F	F	F	F	F	0
9	R	R	F	F	F	F	F	0
10	F	F	P	F	F	F	F	0
11	P	F	P	F	F	F	F	0
12	R	F	P	F	F	F	F	0
13	F	P	P	F	F	F	F	0
14	P	P	P	F	F	F	F	0
15	R	P	P	F	F	F	F	0
16	F	R	P	F	F	F	F	0
17	P	R	P	F	F	F	F	0
18	R	R	P	F	F	F	F	0
19	F	F	R	F	F	F	F	0
20	P	F	R	F	F	F	F	0





Exploratory Analysis

Data Set 1

Test	Fail	Pass	Repair
AOI1	0	17505	1719
AOI2	52	18799	373
FT1	0	15527	3697
FT2	309	18892	23
FT3	299	18925	0
HV	2	19202	20
UT	4	19013	207

Data Set 2

Test	Pass	Repair	Fail
AOI (Vision)	2213905	606315	0
FT (Function)	2059030	21813	40115
H.V (High Volt)	724244	2012	241
M.Load (Unit)	709287	21800	569

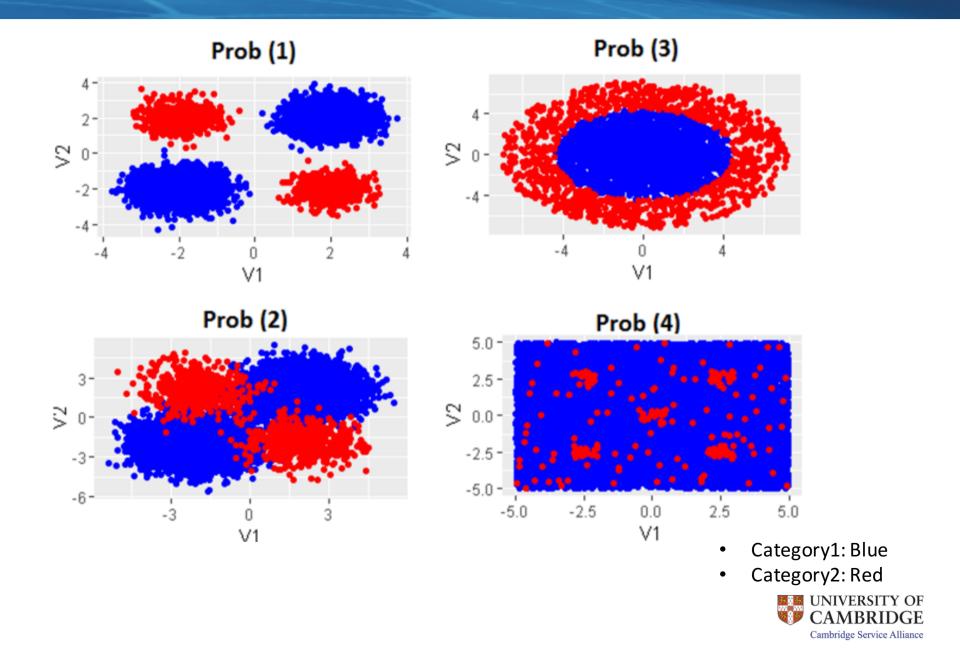
> Primality of failure or repair at Unit test (UT)

• Data Set 1: 0.0108

• Data Set 2: 0.0307



Imbalance and Noise vary among classification problems



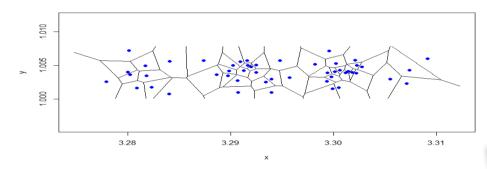
Existing Methods

- ➤ State of the art
- 1. Pre processing methods
 - Resampling
 - Feature extraction (filter and wrapper techniques)
- 2. Cost Sensitive Methods
 - Boosting (adaboost, Gradient boost etc)

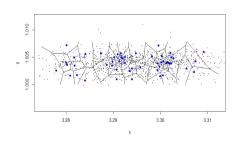


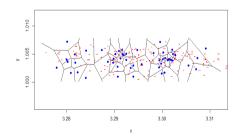
Proposed Methodology: Partition of Information Space and selection of best partition

1. Partition of the feature space through Voronoi tessellation

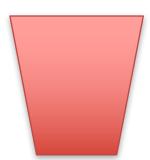


2. Selection of the tiles according to their probability











Proposed Methodology to solve imbalance classification problem

- Selection of Seed points
 Randomly
- LVQ to adjust the seed points

SOM, the unsupervised way of finding the clusters

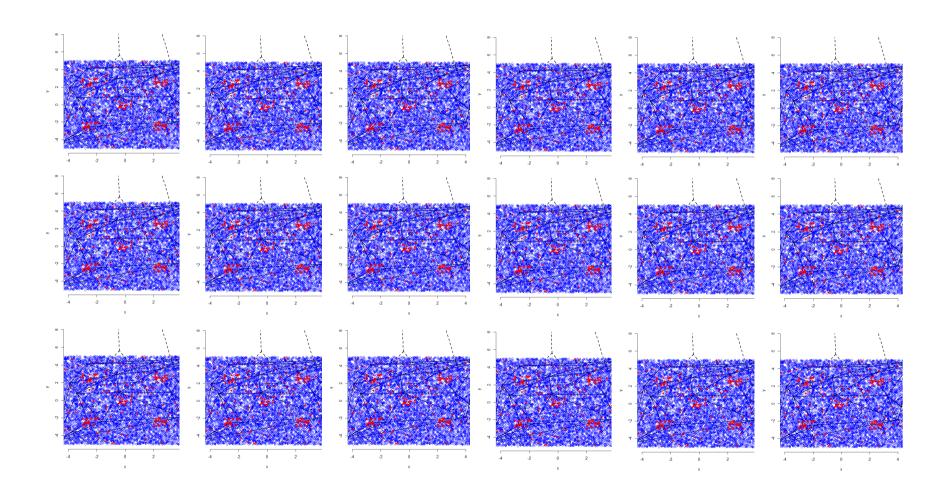
LVQ output as final seed for voronoi tiles

Voronoi tiles are based on the LVQ outputs

- Selecting voronoi tiles with the help of GA
 - Selection of the Number of tiles
 - Selection of Classes need objective function



Proposed Methodology: Partition of Information Space and selection of best partition

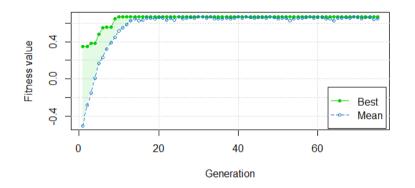




Assigning groups to the tiles (Results)

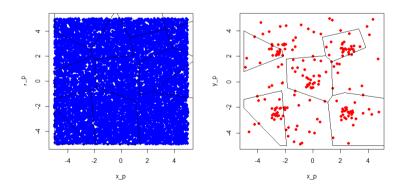
	Class		
Status	B_{pass}	B_{fail}	_
pass	$X_{pass,B_{pass}}$	$X_{pass,B_{fail}}$	$X_{pass.}$
fail	$X_{fail,B_{pass}}$	$X_{fail,B_{fail}}$	$X_{fail.}$
Total	$X_{\cdot,B_{pass}}$	$X_{.,B_{fail}}$	$X_{\cdot \cdot}$

Table 1: Contingency table for partion $\{B_{pass}, B_{fail}\}$



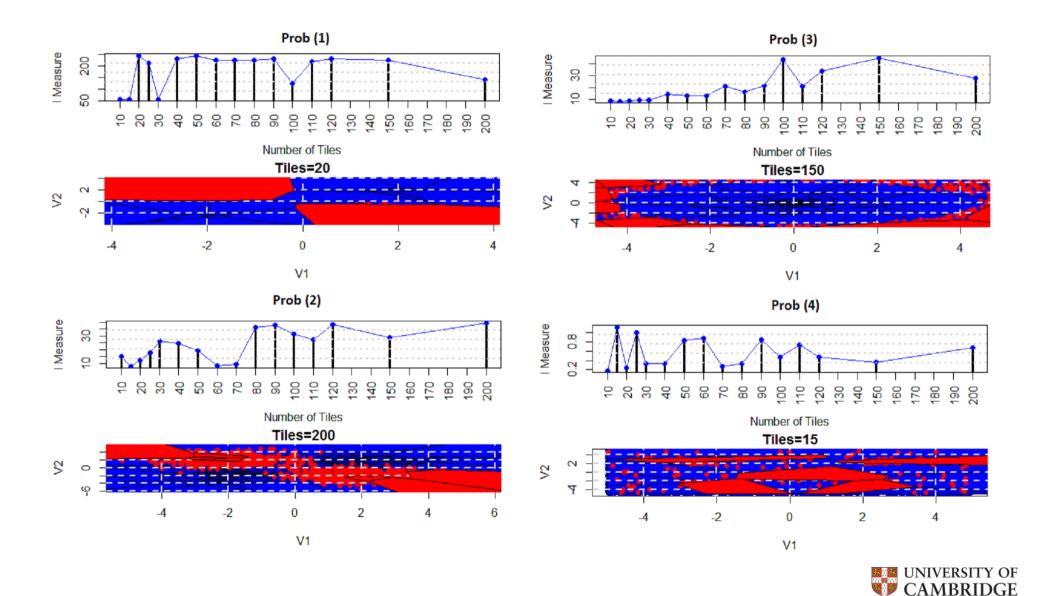
Objective Function

$$I = \frac{L_{fail} - U_{pass}}{(U_{pass} - L_{pass}) + (U_{fail} - L_{fail})}$$



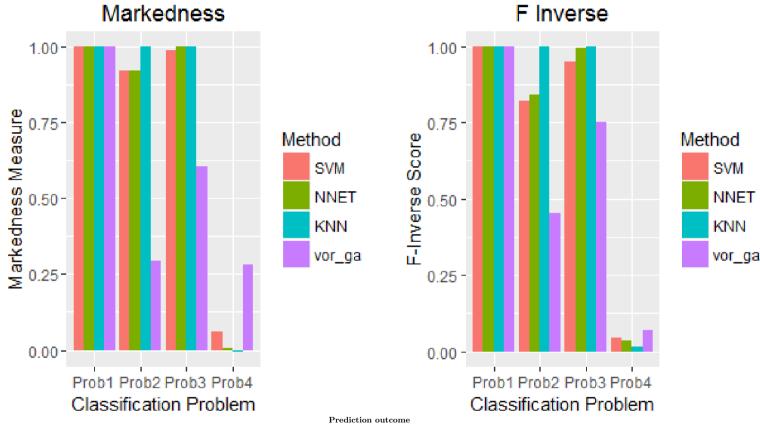


Classification through proposed Methodology (Results)



Cambridge Service Alliance

Performance of the proposed methodology (Results)

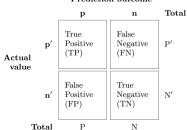


 $\label{eq:markedness} Markedness = Precision + Inverse Precision - 1 \quad (7)$ Where,

 $Precision = \frac{Actual\ Positives \cap Predictive\ Positives}{Predictive\ Predictive\ Provinces}$

By above definition,

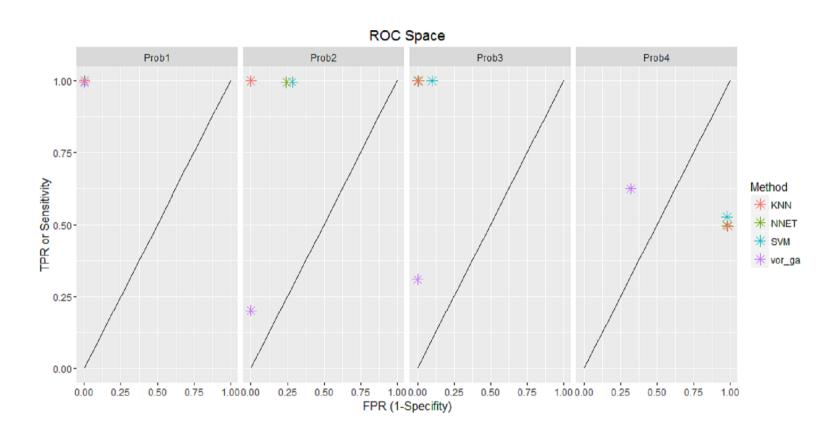
 $Precision = \frac{TP}{(TP+FP)}$ and $Inverse Precision = \frac{TN}{(TN+FN)}$



$$F_1 = rac{2 ext{TP}}{2 ext{TP} + ext{FP} + ext{FN}}$$



Performance of the proposed methodology (Results)



$$FPR = \frac{FP}{N} = \frac{FP}{FP + TN} = 1 - TNR$$

$$TPR = \frac{TP}{P} = \frac{TP}{TP + FN}$$



Conclusion

- > A Novel methodology to classify imbalanced and noisy data
- > Application of methodology in Industrial manufacturing
- ✓ Optimized quality control
- ✓ Optimization of Resources
- ✓ More Knowledge/understanding about process dynamics



Vision of next generation factory

